

# VFA KingFish Reef Phase 1 Proposed Locations

# **Report of Survey**

Report compiled by:T.KAYEDate:3/03/2021





www.totalhydrographic.com.au







Purpose of the Survey

Hydrographic survey of the proposed VFA Kingfish Reef locations.

### General

Survey and ID		Project Locality			
VFA0001		Portsea, VIC			
Survey Authority/Client		Client Contact			
Vicorian Fisheries Association (VFA)		Brent Womersley			
Hydrographic Surveyor (Superv	vising)	Certification or Qualification			
Tim Williams		AHSCP CPHS - Level 2			
Hydrographic Surveyor (Assistin	ng)	Certification or Qualification			
Louis Bennett		Bachelor of Marine Geography			
Start date of Survey	14/02/2021	End Date of Survey	14/02/2021		
Number of field days	1	Class of Survey	N/A		
Survey Platform/Vessel Name		Survey Platform/Vessel Name			
Total 1 - 6.3m Catamaran		-			
Survey Report Completed By		Тот Кауе			
Date of Survey Report Completi	ion	3/03/2021			
<b>Details of Survey Exe</b>	cution				
The following positioning syster	ms were used:				
Positioning System 1		POS MV INS			
Positioning System 2		Leica GS14			
Base station (if applicable)		-			
The following sounding systems	s were used:				
		Model/System Details	Frequency (kHz)		
Echosounder 1		R2Sonic 2020	400kHz		
Sub Bottom Profiler		Innomar SES 2000 Compact			
Motion reference unit		Applanix WaveMaster POSMV	-		
Towed Side Scan Sonar		-	-		
Hull mounted Side Scan Sonar		-	-		
Logging and processing systems	s used, and Versions:				
Logging		Hypack 2020			
Processing		Hypack 2020			
Survey Plan line spacing		SBP: 20m across all extents & 10m across proposed reef			
Has data been thinned from tha	at collected	Yes			
Data - thinning		1m Median Surface Export			
Survey Plan - thinning method a	and bin size	10m Shoal Bias Thinning			
			<u> </u>		



### **REPORT OF SURVEY**

### **Horizontal Control**

Soundings are on the following datum	
Datum	GDA94
Spheroid	GRS80
Projection and Zone	MGA Zone 55
How was the positioning system validated	RTK GNSS Validation against PSM/ Static Position
THU - Total Horizontal Uncertainty. Estimated Accuracy of soundings at 2.45 Sigma (95%) confidence level	2.00m
Vertical Control	

#### Tides Applied **RTK GNSS Tides** Sounding datum Chart Datum (Queenscliff) Geoid details if using GNSS tides AusGeoid09 **AHD Separation Value** 0.625m below AHD Tide Board/Gauge 1 N/A N/A Tide Board/Gauge 2 PAYWIT PM 148 Survey Mark used for datum connection Survey Mark used for datum connection Survey Mark used for datum connection Method for Sound Velocity correction Sound Velocity Profile Temperature and Salinity values used N/A Tide Model comments (if applicable) The following table contains the Survey Control marks used and their associated coordinate uncertainties Survey Mark Orthometric Height Easting Northing PAYWIT PM 148 295826.983 5762221.391 1.266 0.017 0.026 Uncertainty

TVU - Total vertical uncertainty. Estimated vertical accuracy of soundings at 1.96 Sigma (95%) confidence level

0.25m



### **DOCUMENT CONTROL & INFORMATION**

### Document Issuer

### **Tim Williams** | Principal Hydrographer Certified Professional Hydrographic Surveyor – Level 2 (CPHS2)

Address:	14/75 Endeavour Way, Sunshine West Victoria 3020, Australia	
Telephone	0467 055 005	
Email	tim@totalhydrographic.com.au	
Website	www.totalhydrographic.com.au	
Document Revision		

Revision	Issue Purpose	Prepared / Checked	Date
1.0	Report of Survey	Tim Williams	3/03/2021

	List of Acroynms
AHD	Australian Height Datum
MGA	Map Grid of Australia
GDA	Geocentric Datum of Australia
CD	Chart Datum
THU	Total Horizontal Uncertainty
TVU	Total Vertical Uncertainty
SBES	Single Beam Echosounder
MBES	Multibeam Echosounder
GNSS	Global Navigational Satelite System
RTK	Real Time Kinematic
WGS	World Geodetic System



### **PAYWIT PM 148**

### PAYWIT PM 148 🔼

Nine figure	338001480	Status	ОК	Туре	SCN (GDA), Adj.	AHD	
Easting	295826.983	Northing	5762221.391	AHD height	1.266	Zone	55
Latitude	-38° 15' 53.5025"	Longitude	144° 39' 58.4240"	Ellipsoid height	3.713	CSF	1.0001132
Hz uncertainty	0.017	Hz order	3	Vt uncertainty	0.026	Vt order	3
Datum	GDA94	Plan ref	OP 122328				

3

SEC. 6 (1) (c) SURVEY CO-ORDINATION ACT 1958

### PERMANENT MARK SKETCH PLAN

Township Queenseliff \_ Parist Paywit 

MEASUREMENTS ARE IN\_\_\_\_\_\_Inks\_\_\_\_



Established in IF LEVELLED	connection with*.	Cord *Type of 5	astral unity of Works	Ref. No. COS, 4949
Reduced	level of Mark	, Rallways, Board of Works,	to Datum?to Authority, &c., or A	rbitrary.
l certify with the Regu	that the Permanent slations under the S	Marks shown in this sket Survey Co-ordination Act 19	ch have been established of 958 and that the informati	on the ground by me in accordance ion shown hereon is correct.
Department	or Authority_Cro	wn Lands &	Survey_Signature	When is. t
CP.776	76	‡If a Licensed Serveyor	Date the letters LS. to be added	26-2-7/
		TO BE FILLED IN BY TI	HE CENTRAL PLAN OFFICE	
XXXX	SUBBLEM.	Substantian Article	Same Datum R.L.	tiunber 1428
Surveys OP101622 0.P 107886 CP112297 c9 112297	OP.102802 108159 CP 11159 CP 111597	this FM: 0.p 105379	R.L. Copied from	148
Noted on Rec 6173/67	ord Plan	11 MA 11.5.71	Cakjo ro,	See also SUPPLEMENTARY Sketch Sketch
et 34.027 - 60.7	. T.(	<ol> <li>Borough of</li> </ol>	Queenscliff S.	R. & W.S.C.

- 6 HAY 1971



### **GEODETIC CONTROL**

### **OBSERVATION 1**

Date	14/02/2021	Time: (AEST)	15:15
Project Locality	Portsea, VIC	Control Vertical Datum	AHD
Horizontal Datum	GDA94	Map Projection	MGA Zone 55
Survey Mark	PAYWIT PM 148	Survey Mark Locality	Queenscliff, VIC
GNSS Device	GS14	Surveyor	Tim Williams
Correction	SNA MAC RTCM 3.1 (94)	Duration of RTK Observations	120s
# Observations	122	# Baseline Distance	N/A

Results				
	Easting	Northing	Orthometric Height	
Survey Mark	295826.983	5762221.391	1.266	
Survey Mark Uncertainty	0.0	0.026		
GNSS Observation	295826.977	5762221.374	1.272	
Standard Deviation	0.003	0.005	0.009	
GNSS Uncertainty	0.0	0.017		
Variation	0.006	0.017	-0.006	



**Final Comments:** 



## **GEODETIC CONTROL VALIDATION SUMMARY**

Date	14/02/2021	Time: (AEST)	N/A
Project Locality	Portsea, VIC	Control Vertical Datum	AHD
Horizontal Datum	GDA94	Map Projection	MGA Zone 55

Geodetic Control Observation #1					
Survey Mark (SM)	PAYWIT PM 148	Survey Mark Locality	Queenscliff, VIC		
GNSS Device	Leica GS14	Correction	SNA MAC RTCM 3.1 (94)		
Time: (AEST)	0:00	Surveyor	Tim Williams		
Survey Mark XY Uncertainty	0.017	Survey Mark Z Uncertainty	0.026		
GNSS XY Uncertainty	0.008	GNSS Z Uncertainty	0.017		
	Easting	Northing	Orthometric Height		
Survey Mark (SM)	295826.983	5762221.391	1.266		
GNSS Observation	295826.977	5762221.374	1.272		
Variation	0.006	0.017	-0.006		

Results				
	Easting	Northing	Orthometric Height	
Average Variations	0.006	0.017	-0.006	
RMS of GNSS observations	0.0	0.017		
RMS of PSM Uncertainties	0.0	0.026		
Survey Datum Uncertainty, 95% confidence (1.96σ) 0.019 0.031				

Final Comment:



### **STATIC POSITION VALIDATION**

To validate the positioning system onboard Total Hydrographic's Survey vessel Total 1, a Static Position validation was performed whilst the vessel was ashore. This was carried out using an independent and validated RTK GNSS Rover to compare the survey system IMU Z observation to that from the RTK GNSS.



Survey vessel Total 1 stationary and ashore for static position validation



RTK GNSS observation taken on the IMU Z reference point



RTK GNSS and POS MV observations are taken simultaneously whilst the vessel is stationary and stable

The survey vessel is positioned on a flat, level area with an open sky view. Observations were taken simultaneously by both Applanix POSMV INS and Emlid RTK GNSS Rover for 120 seconds.

![](_page_8_Picture_0.jpeg)

## **STATIC POSITION VALIDATION RESULTS**

Date	14/02/2021	Project	VFA0001
Time: (AEST)	15:00	Project Locality	Portsea, VIC
Vertical Datum	Chart Datum	AHD Separation	0.625m below AHD
Horizontal Datum	GDA94	Map Projection	MGA Zone 55
Static Position Node	POSMV IMU Origin	Validation Location	Queenscliff Boat Ramp
GNSS Device	Leica GS14	Surveyor	Louis Bennett
Correction	SNA MAC RTCM 3.1 (94)	Duration of RTK Observations	120s
# IMU Z Observations	8370	# Baseline Distance	N/A

Results			
	Easting	Northing	Orthometric Height
IMU Z (RTK GNSS)	295637.370	5762362.490	2.878
RTK Rover Uncertainty	0.005		0.006
POSMV Observation	295637.359 5762362.500		2.879
Standard Deviation	0.004	0.006	0.005
POSMV Uncertainty at 95%	0.018		0.010
Variation	0.011	-0.010	-0.001

![](_page_8_Figure_4.jpeg)

**Final Comments:** 

Static Pos observations reduced to AHD for comparison

![](_page_9_Picture_0.jpeg)

### **CROSS LINE STATISTICAL ANALYSIS**

Date	14/02/2021	Project Locality	Portsea, VIC
Project	VFA0001	AHD Separation	0.625m below AHD
Vertical Datum	Chart Datum	Map Projection	MGA Zone 55
Horizontal Datum	GDA94	Number of Cross Lines	1

Cross Line Statistics Results			
	Mean Difference (m)	Standard Deviation	95% Confidence (1.96σ)
Crossline 1	0.000	0.110	0.220
Crossline 2	-		
Crossline 3	-		
RTK GNSS / SBES	-		
Average	0.000	-	-
RMS	-	0.110	0.220

### SCREEN GRABS OF CROSS LINE STASTICS APPLICATION

![](_page_9_Figure_5.jpeg)

#### Discussion:

95% confidence of MBES soundings has been factored into the survey's final Total Vertical Uncertainty (TVU) assessment

![](_page_10_Picture_0.jpeg)

### **BEAM ANGLE STATISTICAL ANALYSIS**

Date	14/02/2021	Project Locality	Portsea, VIC
Project	VFA0001	AHD Separation	0.625m below AHD
Vertical Datum	Chart Datum	Map Projection	MGA Zone 55
Horizontal Datum	GDA94	Number of Cross Lines	1

A beam angle test was undertaken to assess the performance of the MBES system across the entire 256 beams per sonar head. Each beam/beam angle was analysed in Hypack 2020 to assess how the MBES system performs relative to its most reliable beams at Nadir. The beam angle test uses the same cross lines in the cross line statistics.

![](_page_10_Figure_4.jpeg)

#### Beam Angle Result #1

![](_page_11_Picture_0.jpeg)

### **BEAM ANGLE TEST RESULTS**

The beam angle test results show that the data has a uniform 95% confidence of approximately 0.20m across the MBES swath. Some signs of accuracy degradation can be seen on the port outer beams (-55,-60 degrees) which is likely due to the crossline passing over the deep hole in the extents. This validates the system is performing optimally across the entire MBES swath.

**Further Discussion** 

![](_page_11_Picture_5.jpeg)

**Crossline over contours #1** 

![](_page_12_Picture_0.jpeg)

## **TOTAL HORIZONTAL UNCERTAINTY (THU)**

Date	14/02/2021	Project	VFA0001
Vertical Datum	Chart Datum	Project Locality	Portsea, VIC
Horizontal Datum	GDA94	AHD Separation	0.625m below AHD
Survey System	R2Sonic 2020	Map Projection	MGA Zone 55

Total Horizontal Uncertainty has been calculated using all of the following observations. All of these observation values are at a 95% confidence interval. SMES Uncertainties for PSM's have been supplied at the 95% horizontal confidence interval.

The propagation of error sources was computed to give an A Posteriori assessment of Total Horizontal Uncertainty

$$\sigma_z = \sqrt{(\sigma_z)^2 + (\sigma_y)^2}$$

### Summary of Horizontal Components of Survey Accuracy

Absolute Accuracy Sources of Error	Validation	95% Confidence (m)
Geodetic Control to Datum	Geodetic Control	0.019
POSMV Positional Uncertainty	Static Position Validation	0.018
POSMV Uncertainty to Datum	Propagation of above	0.026
Final Sounding Accuracy to Datum	Ground Truth	N/A
Absolute Accuracy	Calculated Value	0.026

Relative Accuracy Sources of Error	Validation	95% Confidence (m)
-		N/A
Relative Accuracy	Calculated Value	

### **Propagation of Errors**

Error Source		95% Confidence Value	
Absolute Accuracy		0.026	
Relative Accuracy		-	
Sounding Accuracy Absolute & Relative		N/A	

The A Posteriori assessment of Total Horizontal Uncertainty unable to be calculated without a relative accuracy assessment. An estimated THU of 2.0m has been assigned to the survey

Total Horizontal Uncertainty (THU)	2.00m

### Comments:

Limited ability to quantifiably assess system relative horizontal accuracy. Due to water depth and complex bathymetry of the survey extents, an estimated THU of 2.0m has been assigned to this survey

![](_page_13_Picture_0.jpeg)

## **TOTAL VERTICAL UNCERTAINTY (TVU)**

Date	14/02/2021	Project	VFA0001
Vertical Datum	Chart Datum	Project Locality	Portsea, VIC
Horizontal Datum	GDA94	AHD Separation	0.625m below AHD
Survey System	R2Sonic 2020	Map Projection	MGA Zone 55

Total Vertical Uncertainty has been calculated using all of the following observations. All of these observation values are at a 95% confidence interval. SMES Uncertainties for PSM's have been supplied at the 95% confidence interval.

The propagation of error sources was computed to give an A Posteriori assessment of Total Vertical Uncertainty

$$\sigma_z = \sqrt{(\sigma_x)^2 + (\sigma_y)^2}$$

### Summary of Vertical Components of Accuracy

Absolute Accuracy Sources of Error	Validation	95% Confidence (m)
Geodetic Control to Datum	Geodetic Control	0.031
POSMV Positional Uncertainty	Static Position Validation	0.010
POSMV Uncertainty to Datum	Propagation of above errors	0.033
Bar check	Bar Check Calibration*	0.04
Final Sounding Accuracy to Datum	Ground Truth	N/A
Absolute Accuracy	Calculated Value	0.052

Relative Accuracy Sources of Error	Validation	95% Confidence (m)
Relative system repeatability - Entire Swath	Cross Line Statistics	0.220
Relative Accuracy	Calculated Value	0.220

### **Propagation of Errors**

Error Source		95% Confidence Value	
Absolute	Accuracy	0.052	
Relative	Accuracy	0.220	
Sounding Accuracy	Absolute & Relative	0.226	

The A Posteriori assessment of Total Vertical Uncertainty was rounded up to give a final TVU of 0.25m

Total Vertical Uncertainty (TVU)	0.25m

#### Comments:

\*Bar check error taken from most recent bar check validation on 22/02/2021

![](_page_14_Picture_0.jpeg)

### **MBES PATCH TEST REPORT**

Date	14/02/2021	Project	VFA0001
Time: (AEST)	9:39	Project Locality	Portsea, VIC
Survey System	R2Sonic 2020	Positioning System	POS MV INS

Surveyors	Tim Williams, Louis Bennett	Vessel Speed (knots)	5kts
Water Depth (m)	15 - 20m	Swath Width	120 <sup>°</sup>
Feature	Sand wave within survey extents		
Files	N/A		

Calibration of the MBES system was conducted at a typical patch test site throughout the duration of the project. The calibration procedure enables the system's reference angle errors to be identified and corrected within the system. After the initial calibration as part of the system mobilisation the same procedure was undertaken as a system validation of the predetermined parameters.

PATCH TEST RESULTS SUMMARY			
	Calibration Value	Validation Result	Status
Port Roll	20.35	20.35	ОК
Starboard Roll	-29.95	-29.95	ОК
Port Pitch	-0.20	-0.20	ОК
Starboard Pitch	0.70	0.20	ОК
Port Yaw	-2.00	-2.00	ОК
Starboard Yaw	-1.50	0.50	CHECK

### PATCH TEST LINE CONFIGURATION OVERVIEW

![](_page_14_Figure_7.jpeg)

### **Final Comments:**

Larger than expected **starboard yaw**. A strong convergence was observed in the Hypack patch test tool, therefore the new value was adopted. This validation result was observed in two patch tests for starboard yaw.

![](_page_15_Picture_0.jpeg)

### **MBES PATCH TEST - ROLL**

#### SCREEN GRABS OF ROLL VALIDATION

#### PORT SONAR HEAD

![](_page_15_Figure_4.jpeg)

### STARBOARD SONAR HEAD

![](_page_15_Figure_6.jpeg)

![](_page_16_Picture_0.jpeg)

### **MBES PATCH TEST - PITCH**

### SCREEN GRABS OF PITCH VALIDATION

#### PORT SONAR HEAD A-B Cross Section and Patch Test - Pitch × \_ x 🖻 P 🔆 🔀 🕇 🗸 🖡 Patch Test Beams Matrix Points olor B Checked Beams ile 18 22.0 Project Level 22.0 0.0 Stacking 2 🔹 22.5 22.5 10 4 11 5 12 Scalin 23.0 23.0 Auto 13 0.0 23.5 14 23.5 0.0 24.0 24.0 Auto Zoom 24.5 Survey 24 ! 1 Brit 09:33:41 02/14/2021 VFA0001 - Kingfish Reef Phase 1 25.0 20 25.0 4++++++++++++260 Second and the life of the state 25.5 26.0 . 26.5 26.5 Z Scale = 3.1 B: 43 A: -3 Patch Test Select O GPS Latency Settings Test and Results Choose Step Size Show History Start Pitch Test Coarse Medium Fine Pitch Initial Offset -0.20 OYaw Adjustment 0.00 Angle/Time Step 0.50 • Head 1 -0.20 Number of Steps Final Offset 21 O Head 2 Vertical Adjustm Test OK 0.00 OBoth Save Test to Histor Step - Step + 2 - patch 2.HSX X=296945.40 Y=5758382.46 Z=26.22 Count=3546

#### STARBOARD SONAR HEAD

![](_page_16_Figure_5.jpeg)

![](_page_17_Picture_0.jpeg)

### **MBES PATCH TEST - YAW**

#### SCREEN GRABS OF YAW VALIDATION

#### PORT SONAR HEAD

![](_page_17_Figure_4.jpeg)

### STARBOARD SONAR HEAD

![](_page_17_Figure_6.jpeg)

![](_page_18_Picture_0.jpeg)

### **CONCLUSION**

#### Feature

A feature was identified on north-west edge of the hole, atop a the shelf at the following coordinates:

Final Survey comments

![](_page_18_Picture_4.jpeg)

### Aspect/Slope Outputs

Aspect and Slope outputs were derived from the final delivered bathymetric dataset. Data was gridded to 2m and imported into QGIS to generate the derived surfaces using QGIS's Raster Slope and Raster Aspect analysis tools.

### Deliverables

VFA0001 MGA94 Z55 Chart Datum 1m Median.xyz Report of Survey.pdf 5 x Survey Plans - Soft Copy

Sheet Number	File Name	Chart Scale / Sheet Size	Sounding Radius
1	VFA0001 - Bathymetry	1:1000 A1	10m Shoal Bias
2	VFA0001 - SBP Contours	1:1000 A1	N/A
3	VFA0001 - Backscatter	1:1000 A1	N/A
4	VFA0001 - Slope	1:1000 A1	N/A
5	VFA0001 - Aspect	1:1000 A1	N/A

In.

Tim WilliamsPrincipal HydrographerCertified Professional Hydrographic Surveyor – Level 2 (CPHS2)

![](_page_18_Picture_12.jpeg)